

## Objective: Non-contact measurement of crops

Image processing software:



[www.mvtec.com/products/halcon](http://www.mvtec.com/products/halcon)

Developed image processing algorithms and  
sensor analysis:

Link for the developed software – see:  
[BSc.-Thesis Alma Gramm, annex 1 to 10](#)

Sensors:

Intel® RealSense™ D435 Camera

Miniaturising of the evaluation unit:

Link for installing Halcon on a Raspberry Pi:  
[https://www.heindl-solutions.com/blog\\_halcon\\_on\\_raspberrypi.htm](https://www.heindl-solutions.com/blog_halcon_on_raspberrypi.htm)

Camera carriers:

1. Farmbot

[www.farmbot.org](http://www.farmbot.org)



2. Boom waterer



Farmbot control software:

Link for the developed software: [B Lab Code No. 20231: Crop and plant height monitoring in greenhouses with a Raspberry Pi, FarmBot and Intel RealSense D435 depth camera](#)

Example of a non-contact measurement of  
crops, data evaluation

Link: [Report Jonas Credner, extended WP](#)